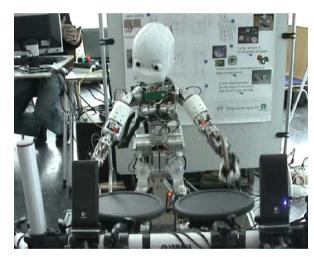
RobotCub Summer School 2008

Sarah Degallier, PhD student in BIRG, EPFL, Lausanne.

I am part of RobotCub project and I work on locomotion, more precisely crawling, but also hand placement during locomotion and reaching on the fours.





As a first test of our controller we have implemented **drumming** on the iCub.



