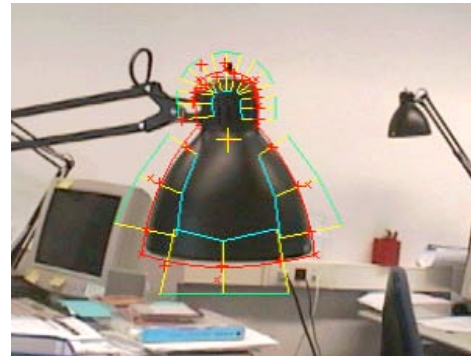


## INTERESTS

- *Robot motion estimation using active contours*
- *Uncertainty estimation*
  
- *Affine cameras geometry*
- *Depth estimation from zooming/foveal-peripheral*
  
- *Object modeling for manipulation in domestic environments*



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